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(54) Radar altimeter.

(57) A radar altimeter (10) incorporates circuitry for automatically adjusting altitude readings for variations caused by altitude and temperature changes. Normal target tracking (32,20,15) of the radar is intermittently interrupted and a calibration sequence is interjected. The current altitude and receiver AGC information at the time of each interruption is temporarily stored (56,101) and a test is initiated in which a pseudo radar return at that altitude is introduced to the receiver (28). The receiver operates on

the pseudo return as it would on an actual return. The transmit power is adjusted automatically for the correct signal level at the tracker. The resultant altitude measured for the pseudo return is compared to a known test altitude and any difference is stored (52) away as a correction factor to be applied to the altitude reading which had been stored at the time that its operation had been interrupted to perform the calibration test.

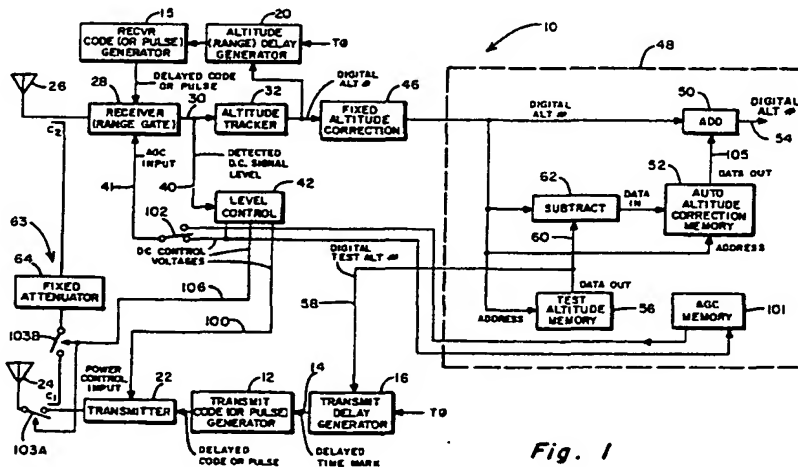


Fig. 1

BACKGROUND OF THE INVENTION

I. Field of the Invention: This invention relates generally to aircraft instrumentation for indicating the altitude of an aircraft relative to the earth's surface and more particularly to a radar altimeter which includes apparatus for calibrating the instrument so as to maintain altitude accuracy under varying operating conditions.

II. Discussion of the Prior Art: A typical prior art aircraft radar altimeter comprises a transmitter which is periodically triggered to generate a pulse of electromagnetic energy which is radiated from a transmitting antenna and a receiver, operatively coupled to a receiving antenna, for receiving an echo or return pulse from a target (ground). Included in the receiver is a closed-loop servo tracker which functions to position a range gate at the leading edge of the return pulse. Further means are provided for measuring the time interval between the transmitted pulse and the range gate, this interval being a measure of the distance to the target.

It is known that such things as temperature variations, return signal strength and range gate width can affect the accuracy of the radar altimeter. Specifically, temperature variations can impact the accuracy of the radar delay timing circuitry as well as various threshold references used in the closed-loop servo tracker. Variations in the signal strength of the return signal and the resultant signal-to-noise variance are known to affect the point on the leading edge of the return signal at which the closed loop tracker positions the range gate.

In the past as taught in the US-A- 3,554,996, these variances have been corrected by providing a test signal at a fixed delay and a fixed amplitude to represent ground return. The altimeter then processes the simulated return and the resulting altitude is compared with the fixed delay to derive the error magnitude. The resulting error is then used to correct the altitude at all altitudes in this group of altitudes. These closed loop systems are only slightly more accurate than earlier open-loop compensated systems because the test signal is set at discrete fixed range delays, not at the actual aircraft altitude, and the test signal amplitude is also set to a pre-determined fixed level at these test altitudes, not at the actual ground return amplitude. When it is considered that it is most essential to safe flying that indicated altitudes be highly accurate at lower flying altitudes, these prior art systems are deficient.

In order to compensate for errors in the altimeter altitude time delay reference, the simulated target must be placed at the present altitude. Further, in order to compensate for altimeter gate overlap errors on the ground return, the signal

strength of the simulated target must correspond to the ground return amplitude, which can vary as much as 50 dB or 100,000 to 1.

It is accordingly a principal object of the present invention to provide an automatic, closed-loop, self-calibration system for appropriately correcting indicated radar target range with particular application to radar altimeter designs requiring high accuracy and to thereby eliminate the need for manual calibration to compensate for extreme variations in temperature and return signal strength.

This object is achieved by the characterizing features of claim 1. Further advantageous embodiments of the inventive radar altimeter may be taken from the dependent claims.

SUMMARY OF THE INVENTION

The above described object is attained in accordance with the present invention by incorporating into the radar altimeter, hardware and software for intermittently injecting very short duration self-calibration sequences into the normal target tracking mode of operation. The present altitude of the aircraft and the present receiver AGC level at the time of interruption is stored and a test is initiated in which a simulated or pseudo radar return at the present altitude at which the aircraft is flying and at the same amplitude as the present ground return is introduced to the receiver. The receiver operates on this pseudo return in the same fashion that it operates on an actual return, i.e., the control tracker servo-loop forces the range gate to track the leading edge of the pseudo return and the receiver gain is maintained by holding the automatic gain control fixed to the level during track, and the simulated target is closed loop adjusted to provide the proper signal level. The resultant altitude measured for the pseudo return is compared to the known test altitude and the altitude difference, if any, comprises an error which is stored in an altitude correction memory for later use in correcting the altitude measured by tracking the ground return. Because all signal paths and associated circuitry signal-to-noise levels, and altitude dependent parameters, such as transmit pulse width, range gate width, duty cycle, and receiver gain used during the calibration phase are the same as those used during normal ground tracking operation, very accurate altitude calibration results. In the same fashion, because the reference clock which controls the simulated or pseudo return delay is the same crystal controlled clock used to position the range gate on the ground return, it can be made accurate within a fraction of a foot.

DESCRIPTION OF THE DRAWINGS

The foregoing features, objects and advantages of the invention will become apparent to those skilled in the art from the following detailed description of a preferred embodiment, especially when considered in conjunction with the accompanying drawings in which:

Figure 1 is a schematic block diagram of a radar altimeter incorporating the automatic calibration circuitry of the present invention;

Figure 2 is a signal diagram helpful in explaining the operation of the altimeter of Figure 1 when operating in a normal ground tracking mode; and

Figure 3 is a signal waveform diagram helpful in explaining the operation of the system of Figure 1 when in its self-calibration mode.

DESCRIPTION OF THE PREFERRED EMBODIMENT

Referring first to Figure 1, there is indicated generally by numeral 10 a radar altimeter incorporating the automatic calibration circuitry of the present invention. It is seen to comprise a transmit code pulse generator 12, the function of which is to generate the transmit modulation code at a time coincident with the transmit timing pulse on line 14. The transmit timing pulse is generated by the transmit delay generator 16, which delay is controlled by a test altitude memory 56 as will later be described. In like manner, the receive code generator 15 generates the receive demodulation code coincident with receive timing pulse generated by the range delay generator 20, which delay is controlled by the altitude tracker 32. Both the transmit delay from generator 16 and the range delay generator 20 receive a marker pulse T_0 as a reference and the delay value of the Transmit Signal Delay 16 determines the time interval following application of the T_0 command that the transmitter 22 is triggered to emit a pulse of electromagnetic energy. In the normal tracking mode, the delay value is zero.

Following a delay interval which is dependent upon the altitude of the aircraft, a radar return signal radiated from antenna 24 will be picked up by the receiving antenna 26 and applied as an input to a radar receiver 28. The output of the receiver is connected by a line 30 to a closed-loop servo tracker 32 which integrates the energy picked up by the receiver, compares the integrated energy to a reference and sets the range delay 20, positioning the receive code to coincide with the leading edge of the coded input return signal to the receiver 28.

Referring to Figure 2, when the radar altimeter of the present invention is operating in its normal ground tracking mode, the transmit delay generator

16 interposes zero delay between the time of occurrence of the transmit command T_0 and the delivery of the transmitter output pulse to the transmitting antenna 24. The transmit pulse is identified by numeral 34 in Figure 2. Some time later, a ground return signal 36 is picked up by the receiver and the tracker 32 controlling the Range Delay generator 20 shifts the range gate timewise so that it is positioned at the leading edge of the ground return signal 36. The aircraft altitude is then proportional to the time interval between the time T_0 and the trailing edge of the range gate 38.

Referring back to Figure 1, it can be seen that the output from the receiver 28 is also applied, via line 40, to a level control circuit 42 which, in its simplest form, comprises an automatic gain control loop which is operative to hold the amplitude of the input signal to the altitude tracker 32 relatively constant. It does so by controlling the transmitter 22 output power level, via the transmit power control input on line 100, and by controlling the gain of the receiver via the AGC input on line 41.

The altitude output from the tracker 32 is coupled not only to the range gate delay generator 20, but to a fixed altitude correction circuit 46, the function of which is to compensate for fixed delay errors including delays attributable to the antenna cables and to the ground-to-antenna height with the aircraft on the ground.

Except for the transmit delay generator, the circuitry thus far described can be considered as somewhat typical of conventional, prior art radar altimeters. The circuitry shown enclosed by the dashed line box 48 in conjunction with the transmit delay generator is added to provide the automatic self-calibration capability. The circuitry shown within the broken line box 48 is represented by functional blocks, but those skilled in the art will understand that the functions can be implemented in a variety of ways including discrete logic or a programmed microprocessor. Thus, limitation to only one such implementation is not intended.

As can be seen in Figure 1, the self-calibration circuitry 48 includes adder means 50 for algebraically summing the output from fixed altitude correction circuit 46 with an altitude correction factor stored in automatic altitude correction RAM scratch-pad memory 52 to provide a correction for all possible altitudes on line 105.

The self-calibration circuitry 48 also includes a test altitude memory 56 which functions to hold the present altitude just prior to initiating the auto-calibration operation and throughout the duration of the short interruptive test sequence. The output from the test altitude memory 56 which is a digital test altitude number is applied over line 58 to the transmit signal delay generator 16 and over line 60 to a subtract circuit 62. The output from the sub-

tract circuit 62 is fed to the automatic altitude correction memory 52.

The self-calibration circuitry 48 also includes an AGC memory 101, which holds the present AGC level just prior to initiating the auto-calibration operation and throughout the duration of the test. Thus, at the start of the test, memory 101 interrupts the normal closed loop AGC path through switch 102 and holds the AGC level on line 41 at the past stored level. It is a further feature that during the test, the transmit power control closed loop, consisting of level control block 42 and line 100, is not interrupted. The result is that the gain of the receiver is held at the previous level experienced in the normal track mode, and the closed loop level control of the transmit power (which becomes the simulated target) automatically sets the simulated return strength to precisely the level of the previous actual ground return.

The self-calibration circuitry 48 also includes a calibration path indicated generally by numeral 63 which includes an RF switch 103B, fixed attenuator 64, and signal couplers C_1 and C_2 disposed between the output of transmitter 22 and the input of the receiver 28. Included in series between the transmitter 22 and the sending antenna 24 is the RF switch 103A. When the system is operating in its normal ground tracking mode, the attenuator 64 and switch 103B act as a very high impedance or an open circuit in the calibration path 63, and switch 103A acts as a very low impedance path connecting transmitter 22 directly to transmit antenna 24. When in its self-calibration mode, however, the level control block 42, via line 106, sets switch 103B to a relatively low impedance value, and 103A to a high impedance value.

OPERATION

The self-calibration of the radar altimeter is a periodic, very short duration, interruptive test initiated preferably by a programmed microprocessor. For example, the test might be run every five seconds, but itself lasts only a few milliseconds. The present tracked altitude appearing at the output of the fixed altitude correction 46 and the AGC level appearing at the level control 42 is stored while the test is being run, and the altimeter is returned to this stored altitude and AGC level, following completion of the test phase. The test itself consists of generating a simulated or pseudo radar return at a known altitude at the altitude at which the aircraft is flying. As will be explained in considerably more detail below, the simulated or pseudo target is tracked by the tracker 32 and the resultant altitude developed by the tracker is compared to the known test altitude. The difference, i.e., the error, is then stored in the altitude calibra-

tion memory 52 where it is subsequently used to correct the output altitude during the ground tracking phase when the aircraft is flying in that particular altitude.

When the system is first powered up with the aircraft on the ground, the altitude correction memory 52 contains a correction of zero feet since no tests have yet been run. The altimeter, in its normal track mode, is tracking the ground return with the AGC level determined by the level control loop. At start of the test, the AGC voltage of the control loop is stored in the AGC memory, the AGC loop is opened, and the stored AGC voltage is applied to the receiver 28. The zero altitude value from the fixed altitude correction circuits 46 is used as an address for the test altitude memory which outputs a delay value on line 58 corresponding to zero feet to adjust the delay from the transmit delay generator 16 from the T_0 reference to correspond to that test altitude. Following the expiration of the delay interval in question, the transmitter 22 is triggered to emit a transmit pulse. Being in the test mode, the switch 103B will be in its low impedance condition allowing the transmitter output to be coupled to the input of the receiver 28. At the same time, the transmitter power level is reduced by the closed-loop level control block to a level resulting in the proper simulated signal level at the tracker, and RF switch 103A reduces the power applied to the transmit antenna 21 to a very low transmitted power level at the antenna and subsequent low ground return signal assuring no interference with the simulated signal. Thus, the simulated test return pulse 59 (Figure 3) is effectively applied to the receiver simultaneously with the generation of the delayed transmit pulse 61. The receiver range gate 28 along with the altitude tracker 32 and the range gate delay generator 20 operates in its normal fashion to align the range gate 63 with the leading edge of the simulated test return. As is clearly evident, the simulated signal applied to the receiver is exactly the same amplitude as the ground return just prior to the test since the receiver gain is the same, and the closed loop controlling the transmit power sets the tracker signal level to its proper level.

Unless the system is in perfect calibration, the altitude derived by the tracker 32 will differ from the test altitude value for the altitude range involved and by subtracting the two in circuit 62, a correction factor results at the output of the subtract circuit 62 which is then stored in the automatic altitude correction memory 52. After each periodic short duration test, the radar altimeter system returns to the mode in which it is tracking the ground return with the correction produced and stored in the altitude correction memory 52 being used to adjust the indicated altitude.

Summarizing, then, when self-calibration is initiated, automatically and periodically, every five seconds, for example, the present position of the range gate 28 is monitored and used to address the test altitude memory 56 and the present AGC voltage value is monitored and stored in the AGC memory 101. A prestored test altitude corresponding to that address is read out from the test altitude memory 56 as a control value for the transmit signal delay generator 16. The transmit signal delay generator 16 then delays the transmit pulse from time T_0 by a time interval equal to the delay value read from the test altitude memory 56. At the same time, the prestored AGC level is read out from the AGC memory 101 and sets the gain of the receiver through switch 102. Also, at the same time, RF switch 103A is set to attenuate the signal applied to the transmitting antenna and switch 103B is set to a low impedance level, allowing the delayed transmit signal to be coupled directly, via calibration path 63, to the receiver 28. The tracker loop positions the range gate on the calibration signal while the level control loop 42 adjusts the transmit power to provide the appropriate signal level. The test altitude stored in test altitude memory 56 is then subtracted at 62 from the tracked altitude signal appearing at the output of the fixed altitude correction circuit 46, producing an altitude error signal which gets stored in the altitude correction memory 52 where it becomes available, via add circuit 50, to later modify the altitude indicated by tracking of the ground return to yield a corrected value.

It is to be especially noted that except for the short length calibration path 63, all signal paths and associated circuitry used during calibration are the same as those used during normal ground tracking operation, thus resulting in very accurate altitude calibration. Moreover, the crystal controlled reference clock (not shown) controlling the simulated target delay 16 is the same reference clock which is used in conjunction with the range gate delay generator 20 to position the range gate on the leading edge of the ground return. Because the calibration path consists of a line length and attenuator diodes whose equivalent radar delay variation with temperature is negligible, the self-calibration feature results in a highly accurate altimeter. By using the same format, i.e., the same transmitted pulse width and duty cycle during calibration as is used during ground tracking and by maintaining the same signal level ratio, the calibration factor established can be reliably used to adjust the altimeter readings as the altitude of the aircraft changes and as the temperature varies.

Claims

1. Aircraft radar altimeter for compensating for changes in operation conditions of the aircraft, comprising:

(a) transmitting means (16,12,22) responsive to a trigger event (TO) for delivering a transmit pulse to a transmitting antenna (24);

(b) receiver means (28) normally coupled to a receiving antenna (26) for receiving a ground return pulse delayed from said triggering event by a first time interval corresponding to the distance between said aircraft and the earth; and

(c) a closed loop tracking means (32,20,15) for alternatively aligning a range gate with said ground return; **characterized by**

(d) a calibration path (63) operative to periodically directly couple said transmitting means to said receiving means;

(e) first memory means (56) for temporarily storing actual tracked altitude values, said memory means being addressed by an address value corresponding to said first time interval;

(f) means (58) for operatively coupling said first memory means to said transmitting means (16,12,22) for generating a pseudo-ground return for said receiving means when said calibration path (63) directly couples said transmitting means to said receiving means, said pseudo-ground return being delayed from said trigger event by an interval corresponding to a discrete altitude read out from said first memory means (56), said tracking means (32,20,15) operating to align said range gate with said pseudo-ground return;

(g) means (62) for subtracting a value corresponding to the interval between said trigger event and said range gate aligned with said pseudo-ground return from said value corresponding to said altitude to develop a correction factor;

(h) second memory means (52) for temporarily storing said correction factor; and

(i) means (50) coupled to said second memory means for modifying said first time interval by said correction factor.

2. Altimeter according to Claim 1, **characterized by** third memory means (101) for storing receiver AGC voltage corresponding to the receiver gain sampled during the first interval measurement.

3. Altimeter according to Claim 1, **characterized in that** the time period that said tracking means (32,20,15) is tracking said pseudo-ground return is substantially less than the

time period that said tracking means is tracking said ground return pulse.

4. Altimeter according to Claim 1 further characterized by level control means (42,101) connectable between said receiving means and said transmitting means for adjusting the transmit power of said transmitting means to maintain a desired signal level at said closed loop tracking means, said desired level corresponding to one at which the amplitude of the signal measured during tracking of the pseudo-ground return is generally equal to the signal level corresponding to an actual ground return pulse.
5. Altimeter according to Claim 4, characterized in that said level control means (42,101) controls said pseudo-ground return level.

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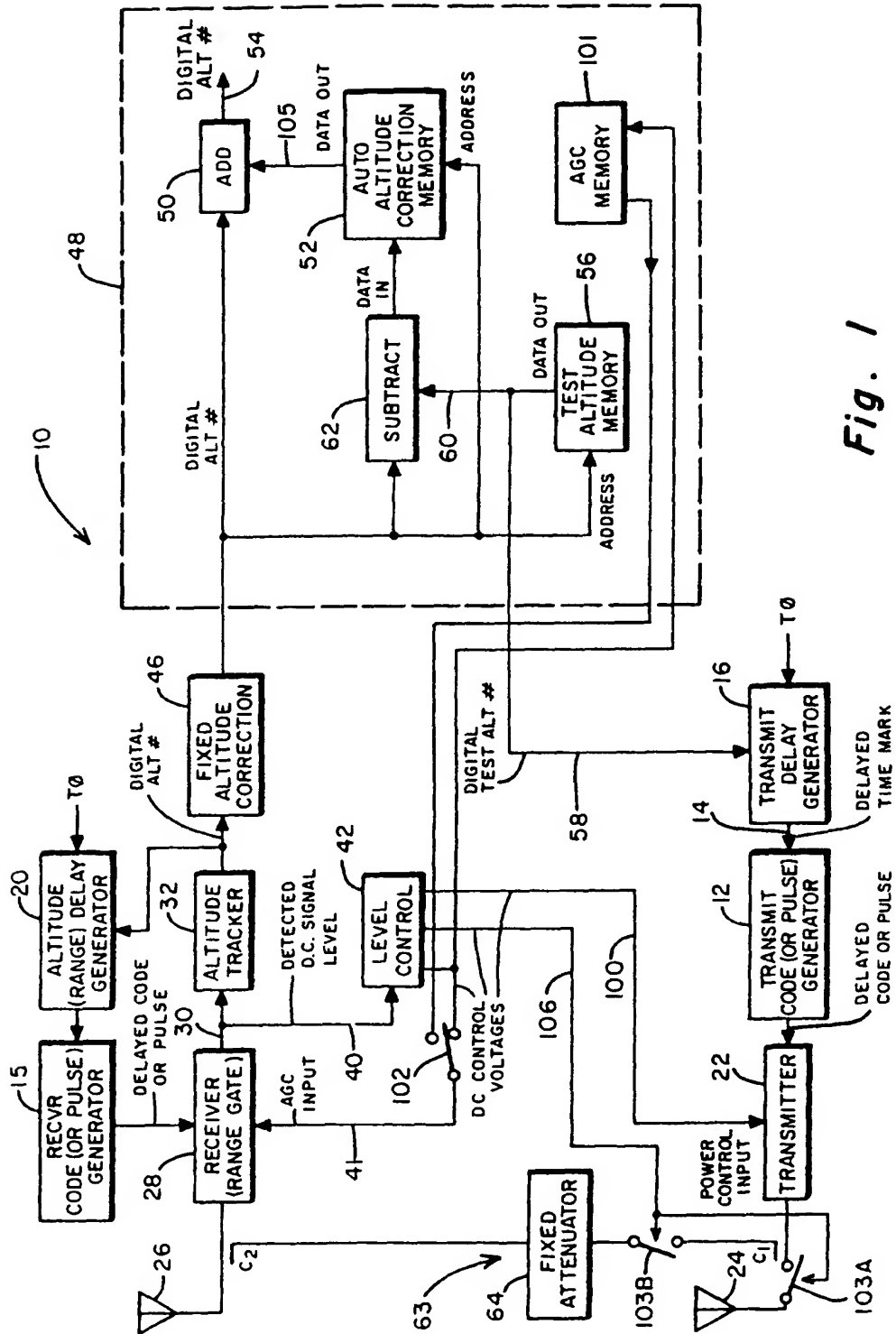


Fig. 1

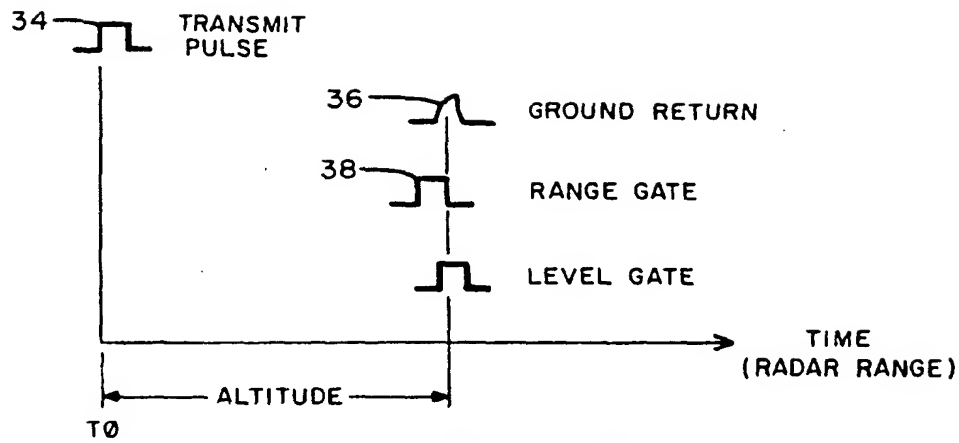


Fig. 2

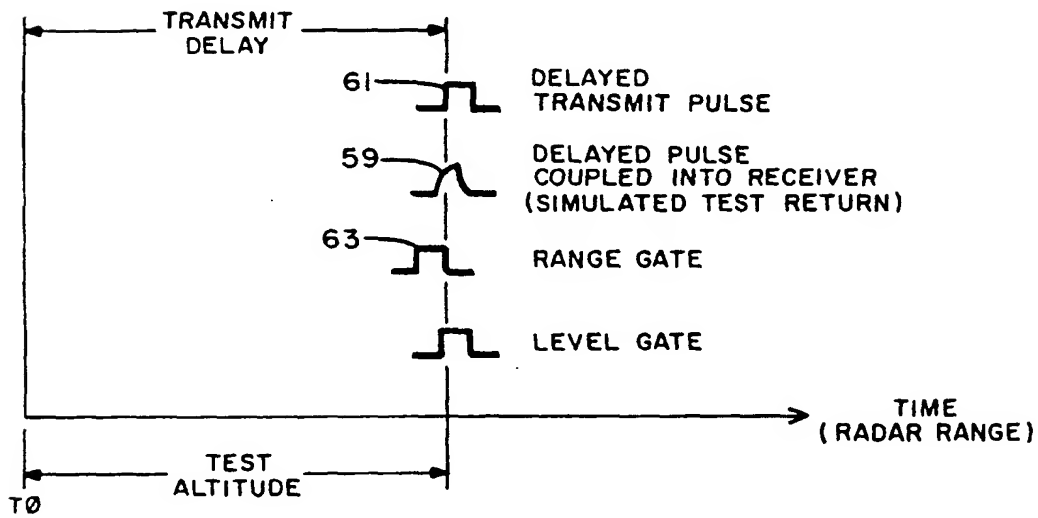


Fig. 3



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54 Radar altimeter.

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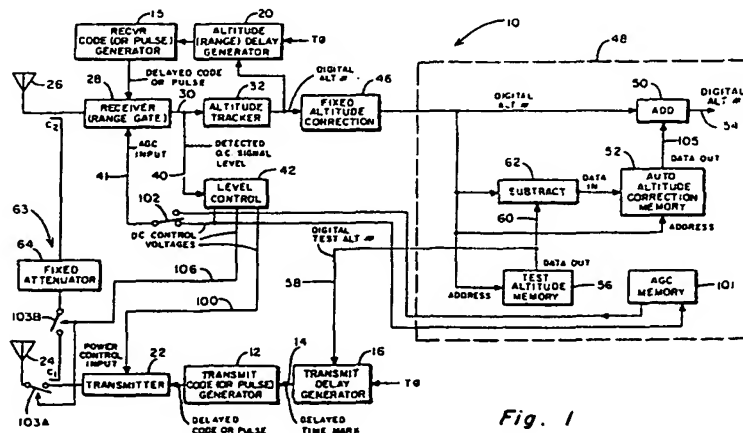


Fig. 1

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European Patent
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EUROPEAN SEARCH REPORT

Application Number

EP 91 11 4204

DOCUMENTS CONSIDERED TO BE RELEVANT			
Category	Citation of document with indication, where appropriate, of relevant passages	Relevant to claim	CLASSIFICATION OF THE APPLICATION (Int. Cl.5)
A	US-A-4 121 213 (BUSH ET AL.) * abstract * * column 2, line 36 - column 6, line 15; figures 1-5 *	1	G01S13/18 G01S7/40
A	US-A-4 053 890 (WOODSON III ET AL.) * abstract * * column 2, line 23 - column 8, line 38; figure 1 *	1	
A	GB-A-2 163 920 (T R T) * abstract * * page 2, line 35 - page 9, line 40; figures 1-6 *	1	
A	US-A-3 544 996 (D. W. PILE) * abstract * * column 2, line 22 - column 9, line 31; figures 1,2 *	1	
			TECHNICAL FIELDS SEARCHED (Int. Cl.5)
			G01S
The present search report has been drawn up for all claims			
Place of search THE HAGUE		Date of completion of the search 19 FEBRUARY 1993	Examiner BLONDEL F.J.M.L.
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